

# 551 030 0xx 0

## Installation Guide SCALAR EVO Flow





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## **Before the Installation**

#### Dear Installer,

This installation guide provides you with installation directives and procedures for the correct installation of the ZF 551 030 0**xx** 0 on-board computer and its installation elements. The 551 030 0**xx** 0 is an on-board computer without a display, installed behind the vehicle dashboard. The 551 030 0**xx** 0 offers:

- A standard Tachograph connection for real-time Tachograph status information.
- An optional CAN Bus connection for monitoring fuel consumption and driving behavior.
- An optional RDD connection for reading out the Tachograph driver card and the mass memory.
- Wireless Bluetooth connectivity.

## Liability

The installation of the on-board computers can be carried out either by technical engineers of ZF, or by a skilled person. A lot of ZF customers prefer to do the installation themselves: the building-in of the on-board computer can then be combined with regular vehicle maintenance services, which allows for a more efficient use of time. To this purpose, ZF provides trainings for the technical engineers of the (installation) company. The training consists of a theoretical part which can be illustrated with a demo installation, and further monitoring. Afterwards, the trainees will be qualified to assemble the other on-board computers in the vehicles autonomously.

Any maintenance/service on the on-board computers should also be performed by a technical engineer of ZF or by a skilled person.

ZF cannot be held responsible for any possible damage ensuing from the correct or incorrect following of the recommendations as listed in this document. Also, the technical engineer remains responsible at all times for the correct installation and connection of the hardware. This manual is but a (partial) recording of, and an addition to, the practical knowledge of the average installer. The illustrations and specific data of non-ZF products have been checked thoroughly and have been found correct at the time this manual was composed. However, ZF cannot accept any responsibility for possible adaptations by the manufacturer concerned. ZF aims for a continuous improvement of its products; for the purpose of technical progress we reserve the right to implement changes at any time, without prior notice.

## Warranty

The housing of each on-board computer is secured against unauthorized opening. Unauthorized access to the unit housing will void the warranty for that specific device.



## **Product Article Code**

551 030 0**xx** 0

Meaning of the **xx** in the part number:

- First **x** 
  - '1' for e-SIM activated
  - **'2**' for plastic SIM activated
- Second **x** 
  - **1-9** = Functional version

## Approvals

## **CE Approval**

See 551 030 0xx 0 EU Declaration of Conformity

## **EEC Type Approval**

E/ECE/324 Addendum 9: Regulation No. 10-06 - E6-10R06 XXXX

#### Disposal



Dispose of hazardous waste in an environmentally friendly manner and in compliance with relevant national regulations.

As with other old devices, all components can be returned to ZF.



## **Best Practices in Installation**

During the entire connection procedure, the voltage must be turned off.

#### ASSEMBLY

The assembly of the parts must be done using the accessories provided. ZF cannot be held responsible for any errors resulting from the use of other materials.

ZF wishes to point out that activities which require welding to the vehicle can cause damage to the electronics of the on-board computer. It is imperative that the device is disconnected when carrying out such activities.

The equipment provided is only suitable for use in locations where children are not likely to be present.

#### **OPENING THE TACHOGRAPH**

If the seal of the Tachograph has been broken during assembly, or if signals from the Tachograph are being diverted to the on-board computer, the Tachograph must be resealed by an authorized organization. ZF and its distributors do NOT accept any responsibility for possible infringements against local legislation.

#### WIRE MANAGEMENT

All the wire ways shall be smooth and free from sharp edges. Wires shall be protected so they do not come into contact with burrs, cooling fins, moving parts, etc., which could cause damage to the insulation of the conductors.

#### FUSES

The positive voltage 12/24 VDC and the positive voltage after contact (ignition) must be protected by a blade fuse of 3A.

Additional fuses should be foreseen by the installer, where needed.

#### **OPERATING CONDITIONS**

Input voltage range: 12/24 V (9 – 32 V) **\*\*\*** Maximum current: 3,0 A Temperature range: -40°C ~ +70°C Ingress Protection: IP5K0 – ISO20653 – IEC60529 Relative humidity between 10 %RH and 90 %RH (non-condensing) Maximum power consumption:

- Power up <30s: 15 W</li>
- Power up >30s: 2 W
- Power down: 0.15 W



## **Installation Flow**

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<u>Connecting the Remote Data Download</u>	
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## Step 1 - Components

Component	Picture	Dimensions (WxHxD)
551 030 0xx 0 on-board computer (Article code: 551 030 0xx 0)		157 x 97 x 27 mm
Power I/O cable (Article code: 551 031 011 0)		RDD and Tachograph wires 2,0m +/-0,05m
Cf. <u>Complete Power Disconnection</u> on page <u>10</u> .		All other wires 3,5m+/- 0,05m
CAN Cable (Article code: 551 031 021 0)		2,0m +/-0,05m
FMS connector kit (Article code: 551 013 011 4)		
RDD connector kit (Article code: 551 013 021 4)		
Tachograph connector kit (Article code: 551 013 031 4)		



## Description 551 030 0xx 0



4. Notches for Cable Ties



## Step 2 – Connecting the Hardware

## **IMPORTANT**

During the whole connection procedure, the voltage must be turned OFF. Only technical engineers who have received installation training by ZF are allowed to handle the on-board computer connections.

## Hardware Connections

All hardware connections can be found on the side of the unit.



#### **COMPLETE POWER DISCONNECTION**

In case of an emergency, the entire unit can be turned off by disconnecting the power I/O connector (4 in the picture above).

Port	No.	Connector	Wire Color	Signal	
••••	1	USB-C			
	2	Digital Output		OUT	
		CAN Bus Connector	Black	CAN LOW	
	3		White	CAN High	
		Power I/O	Black	K31 GND	MANDATORY
			Violet	INPUT 1	
			Pink	INPUT 2	
	1		Grey	RDD LOW	
	-		Red	K30 VBAT	MANDATORY
			Blue	K15 IGNITION	MANDATORY
			Yellow	ТАСНО	
			White	RDD HIGH	

Confidential Information



Port	No.	Connector	Wire Color	Signal	
		RS232 Cable	Yellow	ТХ	
1			Black	GND	
	5		Brown	RX	
			Grey	V OUT	
		RS232 Cable	Yellow	ТХ	
2			Black	GND	
	6		Brown	RX	
			Grey	V OUT	
		7		1	

Port	No.	Connector	Wire Color	Signal	
	7	USB-A			

#### PLEASE NOTE

- Minimal voltage, GND, and ignition must be connected.
- The device is internally fused on the power connections.
- The device should be connected to a 3A fused power supply.

#### CAUTION

Connections must be done with the ignition turned OFF!

YOU MUST NEVER connect K15 IGNITION to the radio contact as this can cause the following problems:



- 1. The Tachograph sends no data if the driver turns the ignition key to the "Radio ON" position. The on-board computer will not receive any status messages from the Tachograph.
- 2. When the driver stops driving and turns the ignition key to the "Radio ON" position, the question "Please choose an activity" will not be displayed on the on-board computer.

SCALAR EVO Flow Installation Guide Confidential Information

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## Connecting to the Standard FMS Connector

## Required Hardware

#### FMS connector kit: Part number: 551 013 011 4

A female standard FMS connector is provided with the on-board computer. In recent trucks, a (male) standard FMS connector is available, where the required signals can be found (K30, K31, K15, CAN- H, CAN-L).

In case no standard FMS connector is available on the truck, you will need to find the signals on another location. Consult the Truck-specific Installation Guides (TIG) for more information on truck-specific signals.



During the entire connection procedure, the voltage must be turned off!

Signal	Pin
GND (31)	1
Ignition (15)	10
Vbat (30)	12
CAN H	6
CAN L	9







## Connecting the Digital Tachograph (D8)

#### OPENING THE TACHOGRAPH

If the seal of the Tachograph has been broken during assembly, or if signals from the Tachograph are being diverted to the on-board computer, the Tachograph must be resealed by an authorized organization. ZF and its distributors do NOT accept any responsibility for possible infringements against local legislation.

## Connection to On-Board Computer

Plug the connector from the Power I/O cable (article code: 551 031 011 0) in the correct port (4) on the side of the unit.



Port	Connector	Wire Color	Signal
4	Power I/O	Yellow	K-Line
		Black	GND

## **Connection to Tachograph**

Connect the K-Line cable (Yellow) from the Power I/O cable (article code: 551 031 011 0) directly to the Tachograph using the Brown connector (Tachograph connector kit (article code: 551 013 021 4)).

Wire Color	Signal	
Black	PIN GND (A5 or A6)	
Yellow	PIN D8 (Tachograph Data)	



## **Connecting the CAN Bus**

## **Connection to On-Board Computer**

Plug the connector from the CAN Bus connector (article code: 551 031 021 0) in the CAN Bus port (3) on the back of the unit.



Port	Connector	Wire Color	Signal
3	CAN Bus Connector	Black	CAN-L
		White	CAN-H

#### PLEASE NOTE

Regardless of what changes you are about to make to the CAN Bus connection, always switch off tension first!



## Connection to CAN Bus via the FMS Interface

### **Connection to CAN Bus**

#### Required on the Truck Side: The FMS Interface

The interface is connected to the CAN Bus through the FMS interface of the truck. Every truck manufacturer has a specific FMS Gateway. This device translates the CAN Bus messages to the FMS standard and acts as a firewall to the truck electronics (security function).

#### The FMS Gateway is delivered, installed, and activated by the truck manufacturer.

Signal	Pin
GND (31)	1
Ignition (15)	10
Vbat (30)	12
CAN H	6
CAN L	9





#### Wiring between the FMS Gateway and the Interface: The CAN BUS Connector

Wire Color	Signal
Black	CAN LOW
White	CAN High



## Connection to CAN Bus using TX-TO-CAN

### PLEASE NOTE

Always *first* turn off the ignition before changes are made to the CAN Bus connection.

## Squarell SOLID

In case no FMS interface is installed on the vehicle, the TX-TO-CAN modules can be used to DIRECTLY connect to the vehicle CAN Bus.



## Connection to On-Board Computer

Use the Squarell Solid CANcliQ cable (551 081 011 0) to connect the Squarell unit to the CAN port (3) on the side of the main unit.



## Squarell Solid CANcliQ cable (551 081 011 0)

## **Connection to CAN Bus**

Connect the CAN wires to the <u>correct</u> location in the truck using the CANcliQ. The CAN Bus wire colors depend on the vehicle type. As a result, we refer to the vehicle passports (provided by your ZF Project Engineer) to find the location of the CAN Bus wires in the truck.

For more vehicle-specific information, go to <u>https://www.mytransics.com/mydocsandtools</u> and consult these instructions:

Squarell installation instructions - heavy commercial vehicles part 1 (a-l) Squarell installation instructions - heavy commercial vehicles part 2 (m-z)



## Connecting the Remote Data Download (RDD)

## Connection to On-Board Computer

Plug the connector from the Power I/O cable (article code: 551 031 011 0) in the correct port on the side of the unit.

C		4 5 6 m - 180 1	<b>b</b> (	
	Port	Connector	Wire Color	Signal
	4	Power I/O	Grey	RDD LOW
			White	RDD HIGH

## RDD via Tachograph

If the Remote Data Download (RDD) signal is NOT available on the FMS, we need to retrieve the RDD data by connecting to the Tachograph.

## Connection to the Tachograph

Connect the grey and white wires from the Power I/O cable (article code: 551 031 011 0) to the C-Connector (red) at the back of the digital Tachograph. A red Tachograph connector (C-Connector) will be provided by ZF (RDD connector kit (article code: 551 013 021 4)).

Wire Color	Tachograph Pin	Signal	Sasa
White	5	CAN-High	
Grey	7	CAN-Low	

## Note

On Scania 2023, an additional modification is required. On the red C-connector, create a loop on pin C7 and C8 to terminate the bus.







## **RDD via FMS**

If the RDD signal is available on the FMS, we can retrieve the RDD data via the FMS interface.

## Connection to the FMS

Connect the grey and white wires from the Power I/O to the FMS interface of the truck (cf. "Connection to CAN Bus via the FMS Interface" p.15).

#### NOTE

To receive the RDD signal, the connection to the FMS must be done through the FMS interface (TX-TO-FMS), not via TX-TO-CAN.

## RDD Tachograph Compatibility

#### VDO

You need to verify if your Tachograph type is compatible with RDD using the version number on the digital Tachograph.

The Tachograph firmware version must be at least **1.3a**.

The digital Tachograph version can be found on the sticker on the Tachograph behind the paper roll of the printer.



#### Stoneridge

The Tachograph firmware version must be at least **SE 5000 7.1**.

The version can be found on a Tachograph printout.



For more information, consult <u>https://help.tx-connect.com/prodB/tx-connect/Content/UIO/English/TX-</u> CONNECT.htm#Troubleshooting/RDD\_Tacho\_compatibility.htm



## **Connecting the Temperature Recorder**

The temperature control system can be installed via TX-Cabled Data Link (TX-CDL). TX-CDL is a direct, wired connection to the temperature control system. The temperature control system is connected to one of the COM ports on the back of the on-board computer (cf. 5 and 6 in picture below).

## **Required Hardware**

RS232 cable (article code: 551 011 031 0)





Supported Temperature Recorders		TX-CDL - Direct Connection
Euroscan TMS	X1	
	X2	TMS9600 / TMS38400
Thermo King i-Box		
REB i-Box		
Thermo King Blue	Box	
Thermo King Trans	Scan	
Thermo King Touch	nLog	
Carrier DataCOLD	500	🗹 Third party
Carrier DataCOLD	600 / Euroscan X3	☑ Partner protocol
Carrier Direct		
TRS		

RS232 Port On-E	Board Compute	r (5/6)	Temperature Recorder
	Wire Color	Signal	Signal
	Yellow	TX 🔨	
-	Black	GND —	
	Brown	RX —	
	Grey*	V OUT	> КХ

#### **IMPORTANT**

Grey wire must be isolated when not connected.



## Euroscan TMS / Euroscan X1/X2

Connect the pins on the ZF device to the correct pins on the connector blocks of the temperature recorder.



		CON	2 Euroscan
RS232 Port 551	030 0xx 0 (5/6)	PIN No.	Signal
Wire Color	Signal	<u> </u>	GND
Yellow	TX	2	RX - COM 2
Black	GND	3	TX - COM 2
Brown	RX	$\rightarrow$ 4	RX - COM 1
		$\rightarrow$ 5	TX - COM 1

#### Note

In case COM1 is already occupied, you need to connect to COM2.

## Setting the Reefer Protocol

After connecting the hardware, the recorder protocol must be set to the correct protocol.

• Direct (CDL) connection: TMS Protocol 9k6 or TMS Protocol 38k4

#### Procedure

- Hold the green button for 3 seconds. The recorder will ask to Enter PIN code (Default PIN code: 1111).
- 2. Next, press the blue button <u>4 times</u> to open Menu 5. Temperature entry settings.
- 3. Press the blue button once to open Menu 11. Communication settings.
- 4. Press the green button once to select EDIT. The Menu 11.1. COM1 settings will be displayed.
- 5. Press the green button once to EDIT.
- Set the correct protocol by pressing the yellow button:
   For Euroscan TMS: press the yellow button until TMS PROTOCOL 9k6 is displayed.
- 7. Press the green button once to confirm your changes.
- 8. Press the red button twice to return to the main menu.



## Thermo King i-Box

The i-Box is an interface between telematics systems and Thermo King controllers and data loggers.

This installation requires the following firmware version:

• Firmware i-Box: REV 5309 or higher

Connect the pins on the ZF device to the correct pins on the connector blocks of the temperature recorder.





RS2	32 Port 551 0	30 0xx 0 (4/6)	Port 2 (	3 <sup>rd</sup> Party)		
	Wire Color	Signal	PIN No.	Signal		2MON
	Yellow	тх —	 → 9	RX		
	Brown	RX —	→19	TX	atta	
	Black	GND —	→ <sub>33</sub>	GND		



## Setting the Reefer Protocol

Normally, the i-Box does not require any specific configuration.

However, in case another system was connected to the i-Box before, it is possible that the protocol needs to be reconfigured to "Third-party protocol" using the Wintrac software on a diagnostic PC/laptop.

More details on the diagnostic software can be obtained from your local Thermo King service partner.

- 1. Connect the COM port of the diagnostic PC/laptop to the i-Box Flash Load Port connector on the i-Box unit.
- 2. Make sure that both the i-Box and the controller/data logger are activated.
- 3. Start the Wintrac software on the PC.
- 4. Select Configure i-Box in the Tools menu.
- 5. Make sure that Third-party protocol is selected under "Protocol Selection".



Serial Number:	000000000000000000000000000000000000000	
Trailer Number:	Protocol Selection:	
Trailer 1	<ul> <li>Third-party protoc</li> </ul>	ol
C Turker 2	C Qualcomp proto	
C Trailer 2	Qualcomm protoc	201
C Trailer 3	C Satellite two-way	protocol
Countdown timer: 72 ho	surs	
Parameter	Value	i-Box Pir
Parameter Current Time Year	Value	i-Box Pir
Parameter Current Time Year Current Time Month	Value 0000 00	i-Box Pir
Parameter Current Time Year Current Time Month Current Date Day	Value 0000 00 00	i-Box Pir
Parameter Current Time Year Current Time Month Current Date Day Current Time Hours	Value 0000 00 00 00	i-Box Pir
Parameter Current Time Year Current Time Month Current Date Day Current Time Hours Current Time Minutes	Value 00000 00 00 00 00 00	i-Box Pir
Parameter Current Time Year Current Time Month Current Time Hours Current Time Hours Current Time Minutes Box Attach Controller	Value 0000 00 00 00 00 \$R2 Controller	i-Box Pir
Parameter Current Time Year Current Time Month Current Time Hours Current Time Hours Current Time Minutes Box Attach Controller Comms Connection Status	Value 00000 00 00 00 00 SR2 Controller 0K	i-Box Pir
Parameter Current Time Year Current Time Month Current Time Month Current Time Minutes Current Time Minutes Box Attach Controller Comms Connection Status Spare Digital Input 11TL	Value 0000 00 00 00 00 SR2Controller 0K Inactive	i-Box Pir          Pin 06
Parameter Current Time Year Current Time Month Current Time Hours Current Time Hours Current Time Hours Current Time Minutes Box Attach Controller Comms Connection Status Spare Digital Input 11TL Spare Digital Input 2 TTL	Value           0000           000           00	i-Box Pir      Pin 06 Pin 07
Parameter Current Time Year Current Time Month Current Time Month Current Time Hours Current Time Minutes Box Attach Controller Comme Connection Status Spare Digital Input 2 TTL Spare Digital Input 2 TTL Spare Digital Input 1	Value 0000 00 00 00 00 SR2 Controller 0K Inactive Inactive 0FF	i-Box Pir       Pin 06 Pin 07 Pin 12
Parameter Current Time Year Current Time Month Current Time Month Current Time Hours Current Time Minutes Box Attach Controller Comms Connection Status Spare Digital Input 2 TTL Spare Digital Input 2 TTL Spare Digital Error Code	Value           0000           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           0K           Inactive           0FF           0           0	i-Box Pir      Pin 06 Pin 07 Pin 12 
Parameter Current Time Year Current Time Month Current Time Month Current Time Minutes Box Attach Controller Comms Connection Status Spare Digital Input 1TTL Spare Dugital Input 2 TTL Spare Dugital Input 2 TTL Spare Dugital Code Keep Alive Output	Value           0000           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           0K           Inactive           0FF           0           0N	i-Box Pir        Pin 06 Pin 07 Pin 12  Pin 30
Parameter Current Time Year Current Time Month Current Time Month Current Time Hours Current Time Hours Current Time Minutes Box Attach Controller Comms Connection Status Spare Digital Input 1TTL Spare Digital Input 2TTL Spare Output 1 Satellike Error Code Keep Alve Output Ibox Wake Up	Value           0000           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           00           0FF           0           0N           0N	i-Box Pir      Pin 06 Pin 07 Pin 12  Pin 30 Pin 28



## **REB i-Box**

The REB i-Box is a motherboard that is mounted on an SR-3 or SR-4 base controller (the motherboard may have a different color than shown in the picture).

This installation requires the following firmware versions:

Firmware i-Box: 5309 or higher •

#### NOTE

Make sure that the i-Box is compatible with the specific reefer/controller unit type and version. For example, the CryoTech reefer compatibility was only added for REB I i-Box REV A031 with firmware version 5506 and for REB II i-Box with firmware version 5370.





1. Find the 3<sup>rd</sup>-party REB wiring harness.



3RD PARTY OR SATELLITE





 Connect the wires of the openend reefer cable to the correct pins on the 3<sup>rd</sup>-party REB wiring harness.



(S232 Port 551	030 0xx 0 (5/6)	310-Pa	ity winng	namess
Wire Color	Signal	Signal	PIN No.	Code
Yellow	TX	→ RX	1	RXD1
Black	GND	→ TX	2	TXD1
Brown	RX	GND	5	COM1

## Setting the Reefer Protocol

Normally, the REB does not require any specific configuration.

However, in case another system was connected to the REB i-Box before, it is possible that the protocol needs to be reconfigured (cf. <u>Setting the Reefer Protocol</u> on page <u>22</u>).



## Thermo King BlueBox

The BlueBox is an interface between telematics systems and Thermo King controllers (SLXi, SLXe, and SLXi SR-3).

This unit requires some modifications to be able to communicate with a thirdparty telematics unit.

First, unplug the standard BlueBox harness from the BlueBox:

- 1. Unplug the 35 BlueBox connector from the BlueBox unit.
- 2. Unplug the 8-pin CAN connector from CAN1.
- Remove all cable ties to remove the wire harness. Be careful not to damage any cables.

Replace the standard BlueBox harness with the **i-BOX harness** (part number **422925**).

- 1. Plug in the i-BOX harness 35 BlueBox connector.
- Plug in the 8-pin CAN connector to the 8-pin CAN1 on the controller. Make sure that the connector clip is secured.











Next, unplug the 8-pin Deutsch plug from the LVD harness of the control box.

3. Now, plug in the 8-pin Deutsch 3<sup>rd</sup>-party connector into the LVD 8-pin connector.

The connections to the on-board computer can be found on the 6-pin 3<sup>rd</sup>-party connector (no.4 in the picture).

RS232 551 030 0x	Port x 0 (5/6)	3 <sup>rd</sup> -Party Connector
Yellow	ΤХ	RX (label RX-01)
Black	GND	GND (label CH-14)
Brown	RX	TX (label TX-01)





## Power and GND Connections

Insert this PWR wire into TERMINAL-RING RED (crimp, solder and insulate) and connect to 2A terminal (J12) pin of SR3 and tighten the nut using a spacer.

Insert this CH wire into TERMINAL-RING BLUE (crimp, solder, and insulate) and connect to CH terminal (J23) of SR3.





## Checking the Installation

In telematics mode, the i-Box LED will blink in the following patterns, depending on whether it is operating correctly or experiencing a failure, while the BlueBox is not in power saving mode.

Operation / Pattern	Frequency
Communication failure	2 blinks per 3 seconds
OK	2 blinks per second

## Direct Connection

On 551 030 0xx 0, the temperature control system is connected to COM 1 or COM 2 on the on-board computer.

Connect the pins on the ZF device to the correct pins on the temperature recorder.

Wire Color	Signal	3 <sup>rd</sup> -Party Connecto
		Signal
Yellow	TX	
		RX
Black	GND 🔨	
		→ TX
Brown	BX	,



## Thermo King TranScan / (TK)DL-PRO

1. Open the temperature recorder to access the connector blocks.





(TK)DL-PRO

2. Connect the wires of the open-end reefer cable to the correct pins on the temperature recorder.

RX	R_RX R_TX
GND	R_GND

15252 port 551 v	010 0XX 0 (5/0)	CON	
Wire color	Signal	Pin No.	Signal
Yellow	TX 🔨	<b>→</b> 1	GND
Black	GND	2	TX
Brown	RX	3	RX

## Setting the Reefer Protocol

The TranScan / TKDL-PRO temperature recorder does not require specific configuration.



## Thermo King TouchLog

#### IMPORTANT

As of 2019-2020, TouchLog replaces TouchPrint Datalogger.

## TouchLog Data Logger



First, please make sure that you are using a Thermo King TouchLog (which supports telematics integration) and <u>not</u> a TouchPrint printer (which does NOT support telematics integration).

There is <u>no visual difference</u> between both units, so you will need to verify your hardware in the device menu via the touchscreen.

Press A next to the screen to consult the Quick Info menu.

In case "TouchPrint printer" is displayed as printer model, your unit is <u>not compatible</u> with 551 030 0xx 0.



OR

Also, when tapping the touchscreen, a different menu will be displayed on a TouchLog printer.



## **Required Firmware Version**





- 1. Open the temperature recorder to access the connector blocks.
- 2. Connect the wires of the open-end reefer cable to the correct pins on the temperature recorder.

S232 Port 551 0	30 0xx 0 (5/6)	CON 2	1
Wire Color	Signal	PIN No.	Signal
Yellow	TX	→ 11	GND
Black	GND	→ 12	RX1
Brown	RX	→ 13	TX1

## Power Connection Thermo King TouchLog

#### **IMPORTANT**

To prevent the TouchLog module from going into sleep mode, you will need to CONNECT THE + SIGNAL TO PIN 2 AND 3 as shown in the picture.

As pin 3 is the ignition, this will prevent the TouchLog module from going into sleep mode. However, the TouchLog module will consume more power, as it no longer goes into standby mode when it is not used.





## Configuring the TouchLog Module

Normally, the TouchLog module should be configured by the Thermo King installer, but in case no info is received from the TouchLog module after connecting it correctly, you should check if it is configured correctly.

## How to Check the Input Configuration

The main screen indirectly shows the configuration of the inputs.

Example: If you see 6 items on the screen, then 6 inputs are enabled.

1. Tap the screen.



/!\

ESC

æ,

2. Next, tap the button to access the configuration menu.

Look for the button to check the input configuration.

#### NOTE

The digital inputs are ground-steered.

## How to Check if the Serial Port on the TouchLog Module is Configured Correctly

1. Tap the screen. DER 2. Next, tap and hold the st e, button for more than 2 seconds to access the ESC service menu. 3. The default password is 10320 (if not correct, contact the installer of the ĒŔ TouchLog module). Esc Next, tap the web button to access the settings of serial port 1. 4. The settings for serial port 1 should look S1 like as shown in the illustration, in order Port type RS-232 to read data from the port. Protocol ModBus Address Baudrate 9600 Parity Ν

1

Stop bit



## Carrier DataCOLD 500

#### NOTE

To have all correct data from the reefer via DataCOLD 500, the following requirements must be met:

• The firmware version of the DataCOLD 500 recorder must be at least version 2.313.

The protocol of the COM port (mostly COM2) for the communication between the reefer unit and the DataCOLD 500 recorder must be set to **Vector**.

 Open the temperature recorder to access the connector blocks.



 Connect the wires of the open-end reefer cable to the correct pins on the temperature recorder.



#### NOTE

In case COM1 is already occupied, you need to connect to COM2.

		PIN No.	Signal
Wire Color	Signal	1	GND
Yellow	TX	2	RX – COM2
Black	GND	3	TX – COM2
Brown	RX	4	RX – COM1



## Setting the Reefer Protocol

After connecting the hardware, the recorder protocol must be set to third-party protocol.

• Direct (CDL) connection: Third-party protocol

#### Procedure

- Hold the green button for 3 seconds. The recorder will ask to Enter PIN code (Default PIN code: 1111).
- 2. Next, press the blue button <u>4 times</u> to open Menu 5. Temperature entry settings.
- 3. Press the blue button once to open Menu 11. Communication settings.
- 4. Press the green button <u>once</u> to select EDIT. The Menu 11.1. COM1 port settings will be displayed.
- 5. Press the green button once to EDIT.
- 6. Press the yellow button until **Third-party protocol** is displayed.
- 7. Press the green button <u>once</u> to confirm your changes.
- 8. Press the red button twice to return to the main menu



## Carrier DataCOLD 600 / Euroscan X3

- 1. Open the temperature recorder to access the connector blocks.
- 2. Connect the wires of the open-end reefer cable to the correct pins on the temperature recorder.



### NOTE

In case COM1 is already occupied, you need to connect to COM2.

			CON 2		
RS232 Port 551 030 0xx 0 (5/6)			PIN No.	Signal	
Wire Color	Signal		<b>1</b>	GND	
Yellow	тх <		2	RX – COM2	
Black		$\leq$	3	TX – COM2	
Brown	BX -		→ <sub>4</sub>	RX – COM1	
Biowin			$\rightarrow$ 5	TX - COM1	
				1	

#### NOTE

To have all correct data from the reefer via DataCOLD 600, the following requirements must be met:

- The firmware version of the DataCOLD 600 recorder must be at least version 3.30.5. •
- The protocol of the COM port (mostly COM2) for the communication between the reefer unit and the DataCOLD 600 recorder must be set to Carrier Advance (not "Vector").



#### Setting the Reefer Protocol

After connecting the hardware, the recorder protocol must be set to Partner protocol.

#### Procedure

- 1. Hold the green button for 3 seconds. The recorder will ask to Enter PIN code (Default PIN code: 1111).
- 2. Next, press the blue button <u>4 times</u> to open Menu 5. Temperature entry settings.
- 3. Press the blue button once to open Menu 11. Communication settings.
- 4. Press the green button <u>once</u> to select EDIT. The Menu 11.1. COM1 port settings will be displayed.
- 5. Press the green button <u>once</u> to EDIT.
- 6. Press the yellow button until **Partner protocol** is displayed.
- 7. Press the green button <u>once</u> to confirm your changes.
- 8. Press the red button twice to return to the main menu.



## **Carrier Direct**

#### IMPORTANT

- Carrier Direct has been tested and validated with models Vector and Supra.
- DO NOT use Carrier Direct on light Carrier models for vans (Xarios, Pulsor, Neos, and so on).
- Other Carrier models must be checked / tested.

Carrier Direct must be connected to the SATCOM port of the reefer.

However, Carrier does not allow removing the SATCOM connector.

Always order the specific connector (for serial connections) to plug in on this SATCOM connector.



SATCOM connector

3MP-27	SATCOM-A SATCOM-B SATCOM-C	A (TX) B (RX) C (GND)	SATCOM
3MP-03	SATCOM-C	C (GND)	

**Connection scheme** 

## **Connection Scheme**





## Additional Requirements

- For **Vector models**, a license needs to be loaded into the reefer to activate the Carrier Direct protocol. The license card to load the license can be ordered at Carrier.
- For **Supra models**, a chip needs to be switched on the reefer controller board. This chip can be ordered at Carrier. Once the chip or license is loaded, one- and two-way communication is enabled on the reefer unit.



## Supra chip



#### NOTE

TRS

To have all correct data from the reefer, the following requirements must be met:

- RS232 must be activated on the TRS unit by opening
   Settings > USB / RS / CAN > COM USB > set to RS232.
- TRS is supported as from 551 030 0xx 0 application version 2.19.
- 1. Open the temperature recorder to access the connector blocks.



2. Connect the wires of the open-end reefer cable to the correct pins at the back of the temperature recorder.



RS232 Port 55	1 030 0xx 0 (5/6)	RS232 Connector
Wire Color	Signal	Signal
Yellow	TX —	→ GND
Black	GND	TX
Brown	RX	RX



## **Connecting the External Smart Card Reader**





ID Card (or Smart Card) Reader for Driver Identification - Part Number: 550 005 005 2



## **Connection to On-Board Computer**

Use the USB-A connection on the side of the on-board computer to connect the Smart Card Reader. Always foresee strain relief for the USB cable using a cable tie.



#### Note

Do NOT use any type of USB hub to connect the card Reader to the interface/on-board computer.

## Installing the Smart Card Reader on the Dashboard

1. First, find a suitable location to mount the Smart Card Reader.

1.	Carefully clean and degrease the installation surface.
2.	The Smart Card Reader must not be exposed to direct sunlight.

2. After cleaning the surface, remove the backing paper (from the backside of the Smart Card Reader) and firmly press the Smart Card Reader onto the surface.





Smart Card Reader (back view - adhesive side)

To achieve a good bond, use the entire adhesive surface of the Smart Card Reader.

- 3. Place the Smart Card Reader with the card reader slot directed toward the front of the vehicle.
- 4. Wait 72 hours after fixing the Smart Card Reader before use.



## Using the Smart Card Reader

#### Νοτε

The ID Card/Smart Card must first be configured in TX-CONNECT. To configure your ID Card in TX-CONNECT see <u>TX-CONNECT Configuration</u> on page <u>42</u>.





## **TX-CONNECT** Configuration

Before you can use your ID Card on the On-Board Computer it must be configured in TX-CONNECT (a back-office application).

# TRALOO12345

## TRA10012345 must be configured in TX-CONNECT

- 1. Log on to TX-CONNECT.
  - a. Log into your TX-CONNECT account.
  - b. Open Settings <sup>™</sup> ► Management ► Drivers
  - c. Select the Driver (that is, the Driver whose ID Card needs to be configured).
  - d. Select the **On-board computer** information tab.
- 2. In the Tacho identification section select the Login with tacho card checkbox.
- In the Tach ID field, enter 000 and then the ID Card alphanumeric number.

#### For Example:

- ID Card Number: TRA10012345
- In Tacho ID field: 000TRA10012345
- 4. Click Save (lower right-hand corner).





## **Connecting PTO**

## **Required Hardware**

++01-17-13 031 FT C BOSCH VZ220-1007	
1 x Relay	5 x Push-on connectors

## **Connection to On-Board Computer**

If you use the PTO functionality, the connections must be made as follows:





## **Connecting the PTO Extension Kit**

Using the PTO extension kit, three additional PTO inputs can be made available for additional applications. For example, SOS button, pump, loading door, and so on.



#### NOTE

The PTO extension kit must be connected to a fused (5A) power supply with suitable 0,75 mm<sup>2</sup> wires.

## **Content of PTO Extension Kit**



## **PTO Connection Table**

Bottom View	Signal	PTO Kit	Vehicle	
	Power	2 / 30	9 - 30V	
5		6 / 31	GND	
	Digital inputs	3 / C	PTO2	
9 - 17		1 / X	PTO3	
C 30 X		4 / 15	PTO4	
31 <b>87A</b> 15	Signal	PTO Kit	OBC	Wire Color
L∎ <u>87</u> ∎H	CAN signal	7 / H	RDD-High	White
		9/L	RDD-Low	Black

Remark: PTO kit contact 5/87A and 8/87 are not used.

	The digital inputs PTO2, PTO3, and PTO4 are ACTIVE HIGH.
IMPORTANT	ON state (> 6.4 V) and OFF state (< 5.0 V).



## **Connection to On-Board Computer**

The PTO extension kit is connected to the RDD port (4) on the on-board computer and must be powered with 9-30 VDC.



Plug the connector from the CAN cable into the correct port (4) located on the side of the unit.

	The PTO extension kit <b>CANNOT</b> be connected to:
IMPORTANT	<ul> <li>The CAN Bus port of 551 030 0xx 0 (port 3)</li> <li>The truck CAN Bus directly</li> </ul>

## No RDD

If RDD is not used, connect the RDD cable to the Power I/O cable (article code: 551 031 011 0) on the on-board computer.

## PTO Connection

PTO Kit	Wire Color Power I/O Cable	Tacho RDD
7 / H	White wire	Vehicle FMS DIGITAL
9 / L	Grey wire	INPUTS

## RDD via Tachograph

If the RDD signal is NOT available on the FMS, then the RDD data can be retrieved by connecting to the Tachograph. In this case, connect the RDD cable to the Power I/O cable (article code: 551 031 011 0) on the on-board computer. The RDD cable is then connected in parallel with the PTO extension kit and the digital Tachograph. To make the parallel connection the RDD cable can be cut.



## **PTO Connection**

Tachograph	PTO Kit	Wire Color Power I/O Cable	Tacho RDD
C5	7 / H	White wire	Vehicle FMS
C7	9 / L	Grey wire	POWER DIGITAL INPUTS

## RDD via FMS

The RDD signal is retrieved from the vehicle FMS Gateway by connecting to the Tachograph.

In this case, connect the RDD cable to the Power I/O cable (article code: 551 031 011 0) on the on-board computer.

The RDD cable is then connected in parallel with the PTO extension kit and the vehicle FMS Gateway.

To make the parallel connection the RDD cable can be cut.



#### **PTO Connection**

FMS Gateway	PTO Kit	Wire Color Power I/O Cable	
CAN-HIGH	7 / H	White wire	Tacho RDD POWER DIGITAL
CAN-LOW	9/L	Grey wire	FMS



## Connecting the SOS Kit



## PLEASE NOTE

All connections must be done with suitable 0.75 mm<sup>2</sup> wires. Connect to a fused (3A) power supply.

## Connection to Interface (No PTO Extension Kit)



Connect the SOS button to INPUT 1 = PTO1 or INPUT 2 = PTO 6 on Connector 4 (see picture above) on the on-board computer.

The SOS button must be powered with a 24V fused power supply.





## **Connection to PTO Extension Kit**

When a PTO extension kit (cf. "<u>Connecting the PTO Extension Kit</u>" p. <u>44</u>) is used, connect the SOS button to the PTO extension kit according to the scheme below.



## Mounting the SOS Button

The SOS button can be installed on the dashboard:

- Panel cut-out diameter: Ø16 mm +-0.2 mm
- Panel thickness: 0.5 mm 6 mm

IMPORTANTDo not mount the SOS button on a surface that may be exposed to directIMPORTANTsunlight.Make sure that the pins from the SOS button do not short-circuit.

## SOS Button – Behavior

Button State	Contact State	Result
Button not pressed	OPEN	Orange LED OFF - PTO state OFF
Button pressed	CLOSED	Orange LED ON - PTO state ON



## Step 3 – Check the Installation

## LED Indicators

LED	Function	Color	Description
		GREEN	GREEN STEADY: Power OK. Contact ON
( <sup>1</sup> )	Power status		GREEN BLINKING: Power OK. Contact OFF
		RED	Power< 6V (truck battery low or installation incorrect.
		GREEN	Connected to the GPRS and to the Server.
(( <b>ę</b> ))		RED	No GSM coverage
	GPR5 status		Not connected to the GPRS.
			Not connected to the Server
0		GREEN	GPS OK (> 6 satellites detected)
•	GPS status	RED	GPS not OK / < 6 satellites detected
		GREEN	CAN connection OK
CAN	CAN connection status	RED	CAN connection NOK.
חחח		GREEN	RDD connection OK.
עעא	KDD connection status	RED	RDD connection NOK.
Tacha	Tachograph connection	GREEN	Tachograph connection OK.
Iaciio	status	RED	Tachograph connection NOK.



## Verifying the Installation with TX-CONFIG

TX-CONFIG is only required to verify the installation, not to follow the vehicle.

## Installing TX-CONFIG

The 551 030 0xx 0 installation can be registered and verified using a smartphone with the TX-CONFIG installation app.

Download TX-CONFIG: <u>https://www.tx-connect.com/sites/tx-config/</u>. OR

Scan the following QR code with your smartphone (a <u>QR code Reader app</u> installed on your smartphone is required)



The download URL / QR code is only required once for installing the TX-CONFIG app. After the initial

installation, you can simply start up TX-CONFIG from your smartphone using the kind icon. Press

to view all installed apps on the smartphone (icon depends on the installed O.S.).

#### PLEASE NOTE

TX-CONFIG requires an active Internet connection and is supported on Android 2.3 and all later versions.

Contact the Transics Service Desk in case a problem occurs during the installation.



## Registering and Configuring 551 030 0xx 0

- 1. Launch TX\_CONFIG and log on using the supplied credentials.
- 2. Enter a valid email address and password and press SIGN IN.

#### NOTE

If you do not have a valid user account, contact the Transics Service Desk.

3. Press INSTALL to register the installed 551 030 0xx 0 device.

#### PLEASE NOTE

The GENERATE CODE button and REPAIR button are inactive as these options are not yet available.

The smartphone's barcode scanner automatically launches.

4. Scan the QR code from the label on the 551 030 0xx 0 on-board computer device (located on the front or the backside of the unit).

/elcom	e to TX-CO	NFIG	
Email			
Passwor	d		
	SIGN IN		
Z Damai	nher me		









#### Camera flash/ Flashlight **PLEASE NOTE** Camera If supported by your smartphone, you can use the volume button on the smartphone to activate its Volume up flashlight to improve visibility while scanning. Volume dowr Press "Volume up" to turn the flashlight ON and "Volume down" to turn the flashlight OFF. The volume button can be normally found on the side of your smartphone (depending on device type).

#### **ALTERNATIVELY**

If the QR code cannot be read by the scanner, press Back (that is, the hardware button on the smartphone).

#### Then press ENTER SERIAL NUMBER and manually enter the device's serial code.

The application checks if the scanned / entered serial number is valid.

If the serial number is valid and linked to a customer, the name of the customer appears at the bottom:

## For Example:

#### Assigned to: Transics

- 5. To link the serial number to the vehicle, enter the license plate of the vehicle.
- NEXT to continue. 6. Press

If the serial number is already linked to a vehicle in the back office, the license plate of the vehicle will be filled in already. Modify it, if necessary.

7. Press **NEXT** to confirm.



License plate:
License plate
The device has not yet been assigned to a vehicle. Please enter the license plate or any other vehicle identifier.
Assigned to: Transics - Sky
NEXT
ВАСК

ABC-123
The device has already been assigned to a vehicle. Please confirm or modify the vehicle icense plate. Assigned to: Transics - Sky
NEXT
ВАСК



#### PLEASE NOTE

When logging on to TX-CONNECT, the serial number will be visible in the OBC overview (Settings > Tools > OBC overview).

In this "OBC overview", the created vehicles can easily be assigned to the unassigned serial numbers from the list.

8. Press KM, SPEED & RPM



## <u>Km Source</u>

 Select the correct mileage source from the list.
 This parameter defines the source that 551 030 0xx 0 uses for its mileage (sent to the back office).

	CAN	Only take into account if the
	CAN	CAN Bus is connected.
CAN	Tacho	Only take into account if a
Tacho	Tacho	Tachograph is connected.
GPS		551 030 0xx 0 calculates
Autodetect	GPS	kilometers based on the
		vehicle position.
		551 030 0xx 0 automatically
	AutoDetect	chooses its source based on
		the available sources.

10. Press **NEXT** to continue.





### Speed Source

11. Select the correct speed source from the list. This parameter defines the source that 551 030 0xx 0 uses for its speed (sent to the back office).

	CAN	Only take into account if the CAN Bus is connected (cf. p. <u>14</u> ).
CAN	Tasha	Only take into account if a
Tacho	Таспо	Tachograph is connected.
GPS		551 030 0xx 0 calculates
Autodetect	GPS	kilometers based on the
		vehicle position.
		551 030 0xx 0 automatically
	AutoDetect	chooses its source based on
		the available sources.



12. Press **NEXT** to continue.

#### RPM Source

13. From the list, select the correct RPM source.



14. Press **NEXT** to continue.

#### Km

- 15. The mileage of 551 030 0xx 0 must be set to the value on the Tachograph.
- 16. Press **NEXT** to continue.

#### PLEASE NOTE

Km is only displayed if either "Vehicle", "GPS" or "AutoDetect" was selected in the Km source screen (see above).









#### Mass Memory Connection

20. Select the correct option from the list. Not connected Connected (RDD) Mass memory connection: Not connected NOTE Mass Memory Connection requires the following Tachograph Firmware versions: BACK VDO ≥ version 1.3A • Stoneridge  $\geq$  version 7.1 • Actia: Actia AC965124 ind B, AC966060 ind A, • AC965123 ind B NEXT to continue. 21. Press After all parameters have been entered, an overview is displayed to verify the settings. Km source: Vehicle Speed source: Vehicle RPM source: Autodetect Pulses/km: 1500 Km: 12346 SEND TO DEVICE 22. If all settings are correct, press to VDO < 1.4, StoneR. < 7.3 Mass memory connection: Connected (RDD) confirm and send the configuration to the device. SEND TO DEVICE BAC **Device Health** 

Device Health indicates the status for the following sections:

- Communication
- Entries
- Tacho
- CAN Bus
- GPS

Press an item to display its details. Press **Back** to return to the Device Health overview.





### Communications





## Step 4 – 551 030 0xx 0 Position

## Installing the Interface Behind the Vehicle Dashboard

- Make sure that the top of the device is oriented towards the windows of the vehicle.
- When installing the unit, keep the area around the antennas away from metal or other obstructions as much as possible to avoid signal disturbance.
- As shown in the image, keep min. 25 mm of free space around the unit to ensure GPS coverage.
- Firmly mount the device in its place using cable ties.
- Use the notches on the bottom side of the unit to fix the cable ties. For Example:
  - Under the dashboard
  - In the top cabinet
  - Free space close to the Fuse Box

#### IMPORTANT

Always check all functionalities after each installation.

#### Pay specific attention to the GPS coverage.

To ensure optimal performance, it is crucial to avoid installing the unit in areas where GPS signal reception may be interfered with or shielded. Make sure that you check the GPS coverage outside (not inside a hangar, depot, workshop ...), as structures may reduce GPS reception. **Check this for every installation!** 



#### **IMPORTANT**

- The on-board computer should never be mounted on or shielded by a metal surface.
- The on-board computer should never be mounted close to cable bundles/wiring harnesses (cf. Bad installation position p. <u>59</u>).
- Make sure the on-board computer is mounted at sufficient distance from other electronic devices (for example, DAB radio, ...) to avoid interference.
- The on-board computer may not be exposed to radiated heat (that is, heating vents, heating tubes / pipes ...).
- The on-board computer may not be exposed to direct sunlight for longer periods.
- Make sure that the top of the on-board computer has a clear line of sight toward the sky (cf. picture above) in order to ensure a good GPS and GSM signal quality.
- Do not use the device at an altitude above 2000 meters.
- Avoid the presence of any material within 25 mm around the GNSS antenna, this can disturb the antenna's performance.



## Installation Example

## Good Installation Example







Minimum of 25 mm of free space around the unit

## Good Installation Example



No cabling around the unit



Installed on a PLASTIC surface

## **Bad Installation Example**



Too much cabling around the unit!



Installed on a METAL surface!



## Finalizing the Hardware Installation

## Secure all Connected Wires

After connecting the power cable and all other hardware (CAN Bus, digital Tachograph, and so on) to the interface, ZF recommends using cable ties to relieve tension from the connectors.



Secure the power cable and all other connectors (FMS, RDD, and K-Line) using a cable tie.

The cable tie can be fixed to the cable tie rings on the corners of the interface.



## **Contact Information**



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If further information or documentation is required, please contact the support department: <u>https://www.zf.com/products/nl/cv/fleet/get\_in\_touch/support\_page.html</u>

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